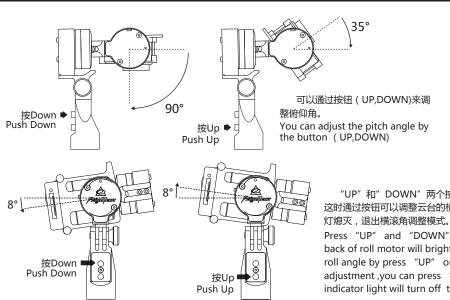
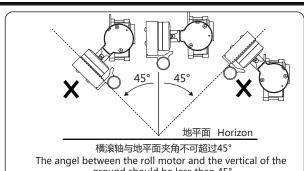




# G3 Steadycam Installation Instructions G3云台手持件安装说明书

Applicable to the firmware V1.25 and above version 适用于V1.25及以上版本固件





ground should be less than 45° "UP"和"DOWN"两个按钮同时按下3秒,云台横滚电机后面的指示灯红灯常亮,进入横滚调整模式。 这时通过按钮可以调整云台的横滚角,调整完毕后,同时按下"UP"和"DOWN"两个按钮3秒,红色指示

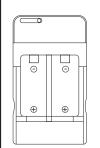
Press "UP" and "DOWN" buttons at the same time for 3 second, the indicator light at the back of roll motor will bright red light. This will enter the roll adjustment mode. You can adjust the roll angle by press "UP" or "DOWN" button (The adjustable range :  $-8^{\circ}$  to  $+8^{\circ}$ ). After finish the adjustment ,you can press "UP" and "DOWN" buttons at the same time for 3 second, the red indicator light will turn off then exit the roll adjustment mode.

下面几种情况需要进行陀螺仪初始化: (1.)云台启动水平角度上有偏差。 (2.)如果长时间不使用。 (3.)或者温度变化超过20度。 **初始化过程如下:** 先把云台静止放置在桌面上,然后打开电源开关,等待云台启动。大约10 秒后云台工作,陀螺仪初始化完成。

The gyroscope need to make initialization when in following several situation: (1.) When the gimbal activate the level angle have a deviation; (2.) The gimbal has not been used for a long time; (3.) There is a change in environmental temperature of over 20 degrees;

35°

Process of gyro reset: Firstly placed the gimbal on a table and keep static ,then power on the gimbal and wait for the gimbal activate. After about 10second the gimbal begin working, at this time the gyroscope initialization is complete.



#### 充电器

输入: AC 100V-240V 50/60Hz 最大输入:150mA 输出: DC4.2V ---- 600mAh 为了防止火灾或受潮。 以及减少触电的危险。 请不要打开护盖。 如有零部件需维修, 请咨询授权 服务代理商。

# Charger

Input: AC 100V-240V 50/60Hz

Max 150mA Output: DC 4.2V ---- 600mAh

WARNING:

To prevent it from fire or moisture. To reduce the risk of electronic shock. Do not remove cover (or back plate). If any parts need repair, consult an authorized service dealer.



## 可充电电池

型号· 16340

容量: 1800mA

### Rechargeable Battery

Type:16340

Capacity:1800mA

# 更多相关信息可访问飞宇科技官方网站: www.feiyu-tech.com

Please visit the official website of Feiyu-tech to get related information: www.feiyu-tech.com

#### 特性参数:

项目	最小	标准	最大	备注
工作电压	7.0V	12.0V	17.0V	2S~4S LIPO
静止姿态跟踪精度	±0.01°		±0.04°	
运动姿态跟踪精度	±0.1°	±0.02°	±0.5°	
电机过载电流保护			0.8A	
电机过载保护时间			600s	电机过载600s后自动停止工作
电机输出最大力矩 响应时间			330us	
俯仰角可转动角度	- 90°	0°	+ 35°	
横滚角度可转动角度	- 45°	0°	+ 45°	
俯仰角控制速率		10°/S		
重量		128g		手柄重量

# **Tech Specification:**

TECH SPEC	Min-working voltage	Standard working voltage	Max-working voltage	Remark
Working Voltage	7.0V	12.0V	17.0V	2S~4S LIPO
Static attitude tracking accuracy	±0.01°		±0.04°	
Motion attitude tracking accuracy	±0.1°	±0.2°	±0.5°	
Overload protection			0.8A	
Overload protection time			600s	After overloaded 600s, Gimbal will stop working automatically.
Max-torque response time			330us	
Controlled pitch angle accuracy	- 90°	0°	+ 45°	
Controlled Roll Angle Accuracy	- 45°	0°	+ 45°	
Pitching Angle control rate		10°/S		
Weight		128g		Handle weight

